

# **Computer Graphics Attributes**

## **Computer Graphics Attributes**

- Line and Text Attributes
  - Fonts in Windows
- Area Fill
  - Boundary/Flood Fill Algorithms
  - Scanline Polygon Fill Algorithm

## Attributes

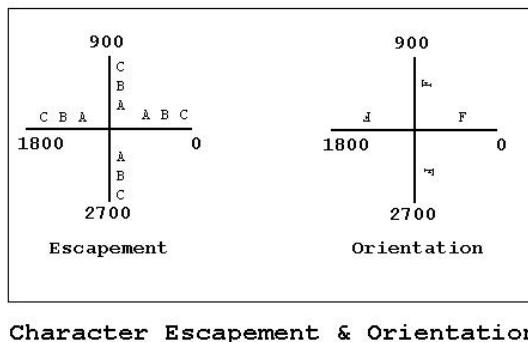
- ☛ How primitives are to be displayed
- ☛ Most systems use modal attributes
  - Values in effect until changed

## Text Attributes

- ☛ Font (typeface)
  - Character set with particular design style
- ☛ Display style
  - underlined, italic, boldface, outlined, strikeout, spacing, etc.
- ☛ Color
- ☛ Size (width, height)--specified in points
  - Point = 1/72 inch

## Text Attributes, continued

- ❑ Orientation--how much character is rotated
- ❑ Escapement--orientation of line between first & last character in a string



## Line Attributes

- ❑ Color
- ❑ Width
- ❑ Style--solid, dotted, dashed, etc.
  - Can be specified by giving a pattern array
  - e.g., `pat[ ]={1,1,1,1,1,1,0,0}`
  - Repeat this pattern on entire line:
    - $i^{\text{th}}$  pixel along line:
    - `if (pat[i%8]==1) SetPixel(x,y)`
- 
- ❑ In Windows, use a pen (CPen)

## Area Fill

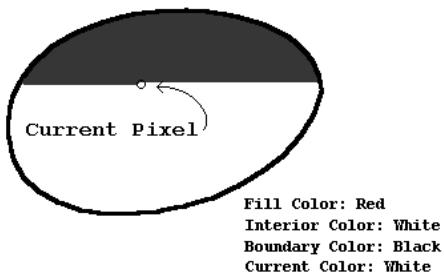
- ☞ Important for any closed output primitive
  - Polygons, Circles, Ellipses, etc.
- ☞ Attributes:
  - fill color
  - fill pattern
- ☞ 2 Types of area fill algorithms:
  - Boundary/Flood Fill Algorithms
  - Scanline Algorithms

## **Area Fill Algorithms**

- ☞ See CS-460/560 Notes Web Page
- ☞ Link to:
  - Week 5-BC: Area Fill Algorithms
- ☞ URL:
  - <http://www.cs.binghamton.edu/~reckert/460/fillalgs.htm>

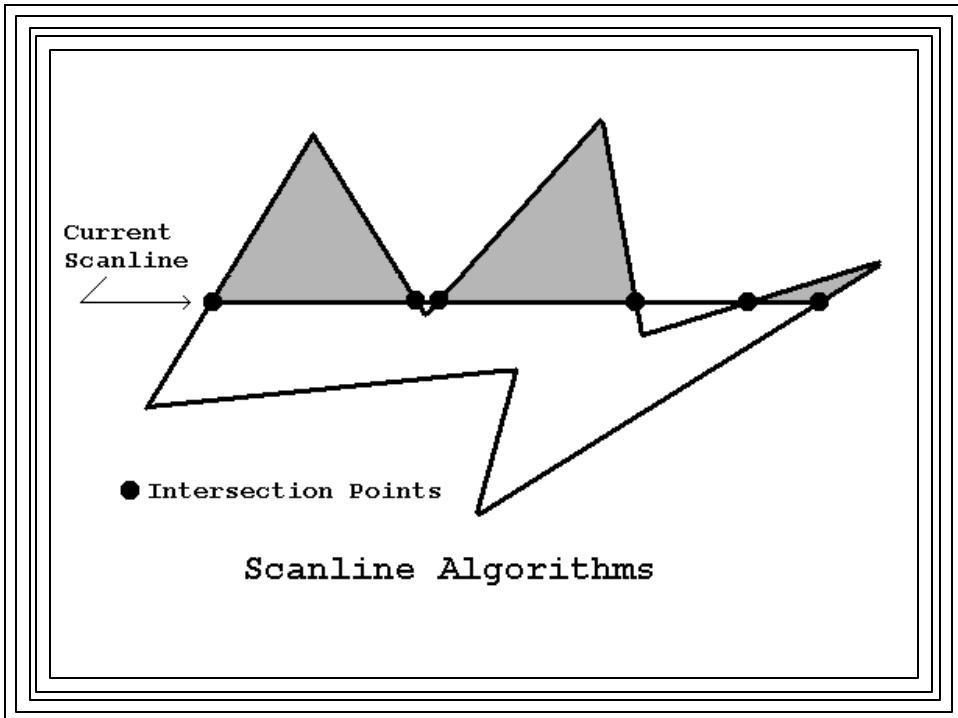
## Boundary/Flood Fill Algorithms

- ⌘ Determine which points are inside from pixel color information
  - e.g., interior color, boundary color, fill color, current pixel color
  - Color the ones that are inside.



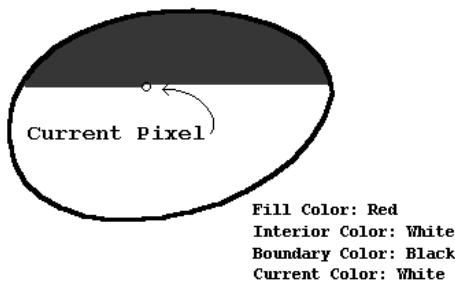
## Scanline Algorithms

- ⌘ Examine horizontal scanlines spanning area
- ⌘ Find intersection points between current scanline and borders
- ⌘ Color pixels along the scanline between alternate pairs of intersection points
- ⌘ Especially useful for filling polygons
  - polygon intersection point calculations are very simple and fast
  - Use vertical and horizontal coherence to get new intersection points from old



## Boundary/Flood Fill Algorithms

- ❖ Determine which points are inside from pixel color information
  - e.g., interior color, boundary color, fill color, current pixel color
  - Color the ones that are inside.



## **Connected Area Boundary Fill Algorithm**

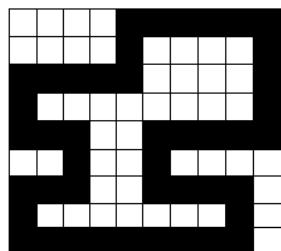
- ☛ For arbitrary closed areas
- ☛ Input:
  - Boundary Color (BC), Fill Color (FC)
  - (x,y) coordinates of seed point known to be inside
- ☛ Define a recursive BndFill(x,y,BC,FC) function:
  - If pixel(x,y) not set to BC or FC, then set to FC
  - Call BndFill() recursively for neighboring points

- ☛ To be able to implement this, need an inquire function
- ☛ e.g., Windows GetPixel(x,y)
  - returns color of pixel at (x,y)

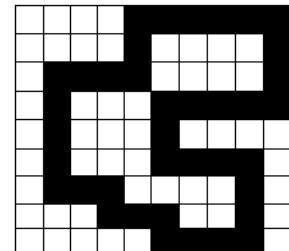
## The BndFill() Function

```
BndFill(x,y,BC,FC)
{
    color = GetPixel(x,y)
    if ( (color != BC) && (color != FC) )
    {
        SetPixel(x,y,FC);
        BndFill(x+1,y,BC,FC);  BndFill(x,y+1,BC,FC);
        BndFill(x-1,y,BC,FC); BndFill(x,y-1,BC,FC);
    }
}
```

- ☞ This would be called by code like:  
BndFill(50,100,5,8); // 5,8 are colors
  - Windows GDI: colors are COLORREFs
  - RGB() macro could be used
- ☞ As given, only works with 4-connected regions
- ☞ Boundary must be of a single color
  - Could have multiple interior colors



A 4-connected Region



An 8-connected Region

## Flood Fill Algorithm

- ☛ A variation Boundary Fill
- ☛ Fill area identified by the interior color
  - Instead of boundary color
  - Must have a single interior color
- ☛ Good for single colored area with multicolor border

## Ups & Downs of Boundary / Flood Fill

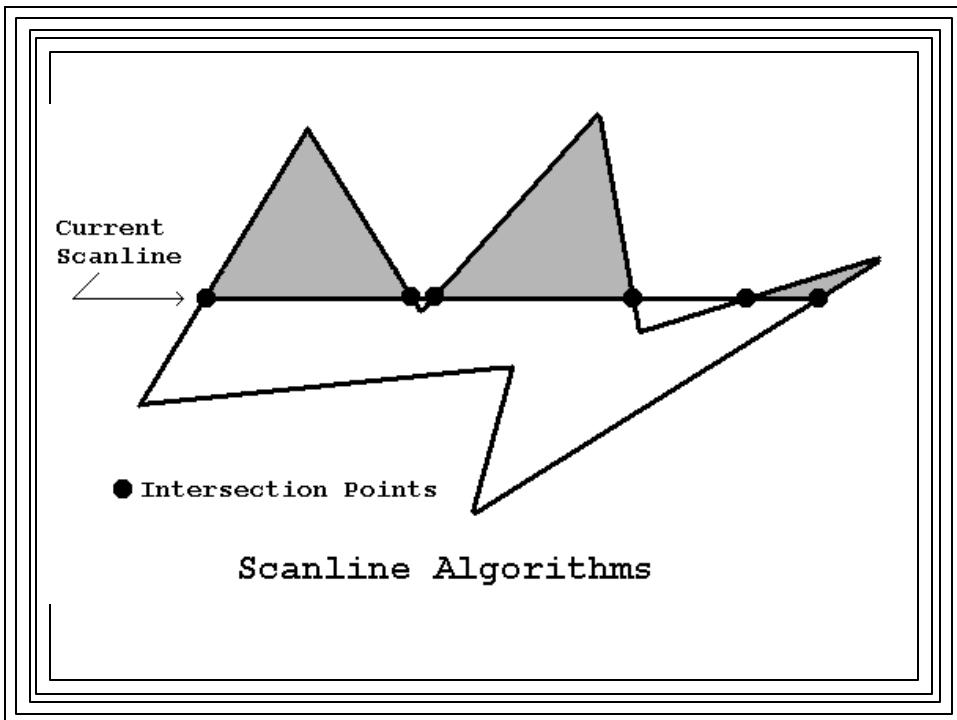
- ☛ Big Up: Can be used for arbitrary areas!
- ☛ BUT-- Deep Recursion so:
  - Uses enormous amounts of stack space
    - (Adjust stack size before building in Windows!)
- ☛ Also very slow since:
  - Extensive pushing/popping of stack
  - Pixels may be visited more than once
  - GetPixel() & SetPixel() called for each pixel
    - 2 accesses to frame buffer for each pixel plotted

## Adjusting Stack Size in VC++

- ↗ ‘Project’ on Main Menu
  - Properties
    - Configuration Properties
    - Linker
  - System
    - Stack Reserve Size:  
perhaps 10000000
    - Stack Commit Size:  
perhaps 8000000

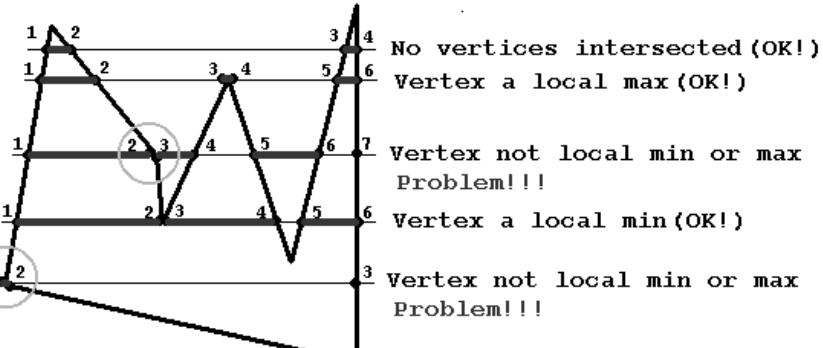
## Scanline Polygon Fill Algorithm

- ↗ Look at individual scan lines
- ↗ Compute intersection points with polygon edges
- ↗ Fill between alternate pairs of intersection points



## More specifically:

- ↗ For each scanline spanning the polygon:
  - Find intersection points with all edges the current scanline cuts
  - Sort intersection points by increasing x
  - Turn on all pixels between alternate pairs of intersection points
- ↗ But--
  - There may be a problem with intersection points that are polygon vertices



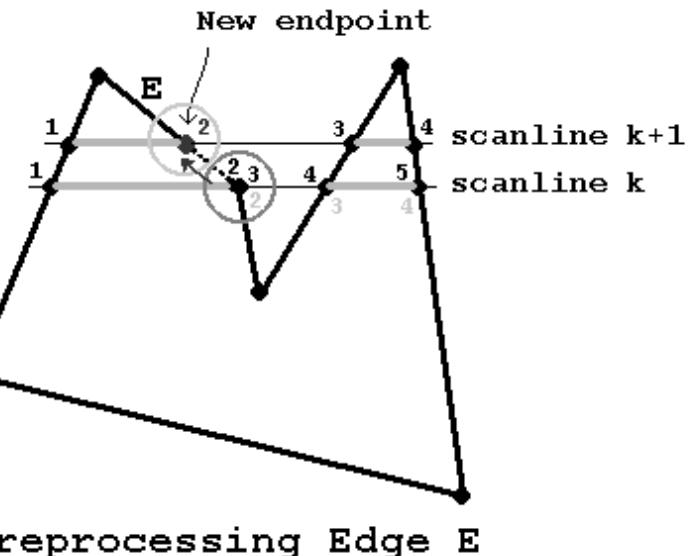
Dealing With Vertex Intersection Points

**Vertex intersection points that are not local max or min must be preprocessed!**

## Preprocessing non-max/min intersection points

- ✉ Move lower endpoint of upper edge up by one pixel
- ✉ i.e.,  $y \leftarrow y + 1$
- ✉ What about x?  
 $m = ?y/?x$ , so  $?x = (1/m) * ?y$   
 But  $?y = 1$ , so:  
 $x \leftarrow x + 1/m$

## Preprocessing



## Active Edge

- ↗ A polygon edge intersected by the current scanline
- ↗ As polygon is scanned, edges will become active and inactive.
- ↗ Criterion for activating an edge:  
 $ysl = y_{min}$  of the edge  
(Here  $ysl = y$  of current scanline)
- ↗ Criterion for deactivating an edge:  
 $ysl = y_{max}$  of the edge

## Vertical & Horizontal Coherence

- Moving from one scanline to next:
  - $y = y + 1$
  - If edge remains active, new intersection point coordinates will be:
$$y_{\text{new}} = y_{\text{old}} + 1$$
$$x_{\text{new}} = x_{\text{old}} + 1/m$$
$$(1/m = \text{inverse slope of edge})$$

## Scanline Polygon Fill Algorithm Input

- List of polygon vertices  $(x_i, y_i)$

## Scanline Polygon Fill Algorithm Data Structures

### 1. Edge table:

- For each edge: edge #, ymin, ymax, x, 1/m

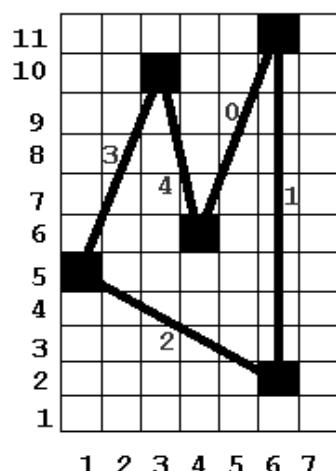
### 2. Activation Table:

- (y, edge number activated at y)
  - Provides edge(s) activated for each new scanline
  - Constructed by doing a "bin" or "bucket" sort

### 3. Active Edge List (AEL):

- Active edge numbers sorted on x
  - A dynamic data structure

## Bin Sort for Activation Table



Edge Table

e	ymin	ymax
0	6	11
1	2	11
2	2	5
3	5	10
4	6	10

Activation Table

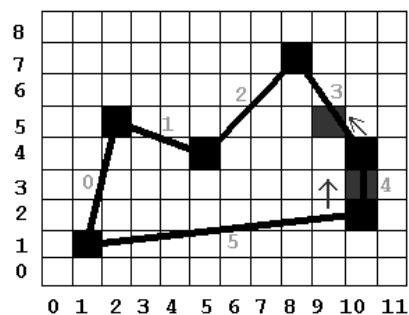
y	activated edge
2	1 2
3	2
4	3
5	0 4
6	

## Scanline Polygon Fill Algorithm

1. Set up edge table from vertex list; determine range of scanlines spanning polygon (miny, maxy)
2. Preprocess edges with nonlocal max/min endpoints
3. Set up activation table (bin sort)
4. For each scanline spanned by polygon:
  - Add new active edges to AEL using activation table
  - Sort active edge list on x
  - Fill between alternate pairs of points (x,y) in order of sorted active edges
  - For each edge e in active edge list:
    - If ( $y \neq y_{max}[e]$ ) Compute & store new x ( $x+=1/m$ )
    - Else Delete edge e from the active edge list

### Scanline Polygon Fill Algorithm Example

`poly={1,1, 2,5, 5,4, 8,7, 10,4, 10,2, 1,1}`



edge	x1	y1	x2	y2	sgn(Dy)
0	1	1	2	5	+
1	2	5	5	4	-
2	5	4	8	7	+
3	8	7	10	4	-
4	10	4	10	2	-
5	10	2	1	1	-
0	1	1	2	5	+

Activation Table						
Y	1	2	3	4	5	6
activated edge #s	0	4	1	3		
	5		2			

Edge Table				
edge	1/m	ymin	x	ymax
0	1/4	1	1	5
1	-3	4	5	5
2	1	4	5	7
3	-2/3	4→5	10→9 1/3	7
4	0	2→3	10→10	4
5	9	1	1	2

## Scanline Poly Fill Alg. (with example Data)

Edge Table (As Algorithm Executes)				
Edge	1/m	ymax	ymin	x
0	1/4	5	1	1, 1.25, 1.5, 1.75, 2
1	-3	5	4	5, 2
2	1	7	4	5, 6, 7, 8
3	-2/3	7	5	9.33, 8.67, 8
4	0	4	3	10, 10
5	9	2	1	1, 10

Active Edge List (As it develops)							
Y	1	2	3	4	5	6	7
Active Edges	0, 5	0, 5	0, 4	0, 1, 2, 4	0, 1, 2, 3	2, 3	2, 3
Fill between	1-1	1-10	2-10	2-5, 5-10	2-2, 6-9	7-9	8-8