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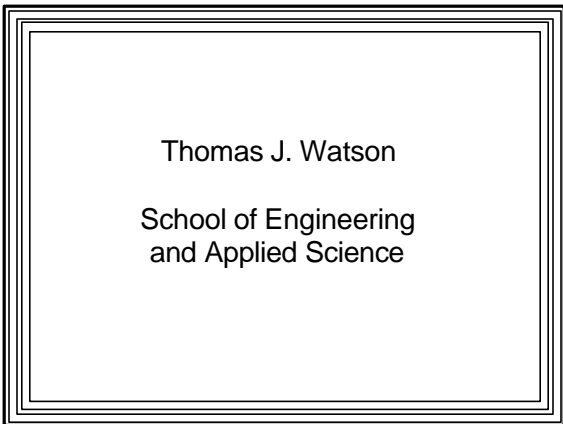
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**CS 560**

**Computer Graphics**

**Professor Richard Eckert**

**Lecture # 10**

**February 21, 2001**

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## Area Fill Algorithms

- Boundary/Flood Fill
- Scanline Polygon Fill
- Scanline Boundary Fill
- Pattern Fill

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## Scanline Polygon Fill Algorithm

- Look at individual scan lines
- Compute intersection points with polygon edges
- Fill between alternate pairs of intersection points

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## More specifically:

- For each scanline spanning the polygon:
  - Find int. pts. with all edges scanline cuts
  - Sort intersection points by increasing x
  - Turn on all pixels between alternate pairs of intersection points
- But--
  - Look at intersection points that are polygon vertices

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No vertices intersected (OK!)  
Vertex a local max (OK!)  
Vertex not local min or max Problem!!!  
Vertex a local min (OK!)  
Vertex not local min or max Problem!!!

Dealing With Vertex Intersection Points

**Vertex intersection points that are not local max or min must be preprocessed!**

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### Preprocessing non-max/min intersection points

- Move lower endpoint of upper edge up by one pixel
- i.e.,  $y \leftarrow y + 1$
- What about  $x$ ?  
 $m = \Delta y / \Delta x$ , so  $\Delta x = (1/m) * \Delta y$   
 But  $\Delta y = 1$ , so:  
 $x \leftarrow x + 1/m$

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### Preprocessing

New endpoint

scanline k+1  
scanline k

Preprocessing Edge E

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### Active Edge

- A polygon edge intersected by the current scanline
- As polygon is scanned, edges will become active and inactive.
- Criterion for activating an edge:  
ysl = ymin of the edge  
(Here ysl = y of current scanline)
- Criterion for deactivating an edge:  
• ysl = ymax of the edge

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### Vertical & Horizontal Coherence

- Moving from one scanline to next:
- $y = y + 1$
- If edge remains active, new intersection point coordinates will be:  
 $y_{new} = y_{old} + 1$   
 $x_{new} = x_{old} + 1/m$   
( $1/m$  = inverse slope of edge)

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### Scanline Polygon Fill Algorithm Input

- List of polygon vertices  $(x_i, y_i)$

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## Scanline Polygon Fill Algorithm Data Structures

1. Edge table:
  - For each edge: edge #, ymin, ymax, x, 1/m
2. Activation Table:
  - (y, edge number activated at y)
    - Provides edge(s) activated for each new scanline
    - Constructed by doing a "bin" or "bucket" sort
3. Active Edge List (AEL):
  - Active edge numbers sorted on x
    - A dynamic data structure

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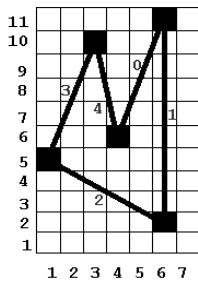
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## Bin Sort for Activation Table



e	ymin	ymax
0	6	11
1	2	11
2	2	5
3	5	10
4	6	10

y	activated edge
2	1 2
3	2
4	3
5	0 4
6	0

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## Scanline Polygon Fill Algorithm

1. Set up edge table from vertex list; determine range of scanlines spanning polygon (miny, maxy)
2. Preprocess edges with nonlocal max/min endpoints
3. Set up activation table (bin sort)
4. For each scanline spanned by polygon:
  - Add new active edges to AEL using activation table
  - Sort active edge list on x
  - Fill between alternate pairs of points (x,y) in order of sorted active edges
  - For each edge e in active edge list:
    - If (y != ymax[e]) Compute & store new x (x+=1/m)
    - Else Delete edge e from the active edge list

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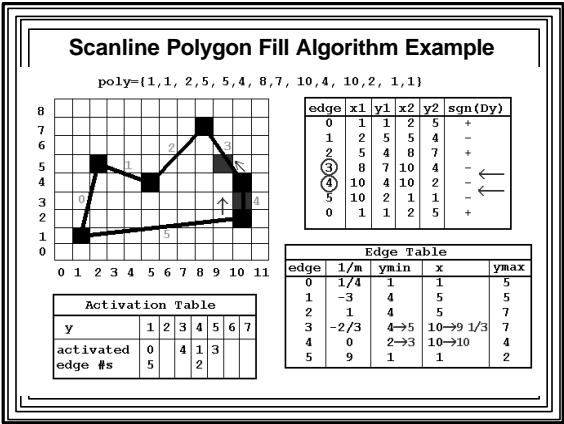
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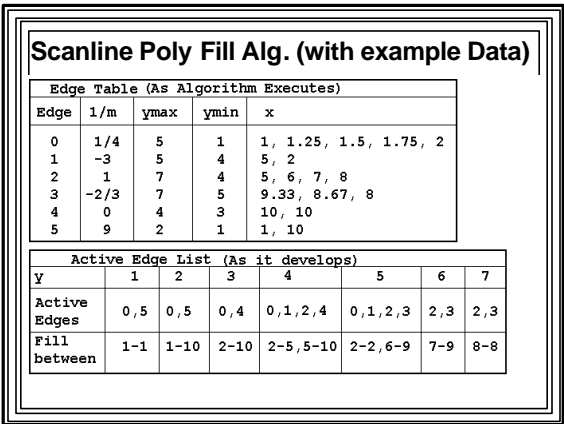
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### Video of Balsa Scanline Poly Fill Algorithm Animator

- Brown University ALgorithm Simulator and Animator
- Mark Brown and Bob Sedgewick
- Scanline Fill Algorithms can be fast if sorting is done efficiently

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## Demo of Scanline Polygon Fill Algorithm vs. Boundary Fill Algorithm

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## Adapting Scanline Polygon Fill to other primitives

- Example: a circle or an ellipse
  - Use midpoint algorithm to obtain intersection points with the next scanline
  - Draw horizontal lines between intersection points
  - Only need to traverse part of the circle or ellipse

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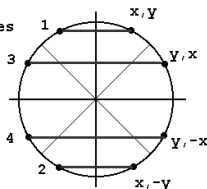
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## Scanline Circle Fill Algorithm

Modify midpoint circle algorithm  
For each step draw 4 horizontal lines

```
Line4(x, y, h, k)
{
  Line(-x+h, y+k, x+h, y+k); // 1
  Line(-x+h, -y+k, x+h, -y+k); // 2
  Line(-y+h, x+k, y+h, x+k); // 3
  Line(-y+h, -x+k, y+h, -x+k); // 4
}
```




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