Photorealism

- Ray Tracing
- Texture Mapping
- Radiosity

Photorealism -- Taking into Account Global Illumination

- Light can arrive at surfaces indirectly
- This light called global illumination
- To now we’ve approximated it with a constant, diffuse ambient term
  - This is wrong
- Need to take into account all the multiply reflected light in the scene
- Two different approaches:
  - Ray Tracing -- specularly reflected light
  - Radiosity -- diffusely reflected light
Photorealism: Ray Tracing

- See CS-460/560 Notes at:
  http://www.cs.binghamton.edu/~reckert/460/raytrace.htm
  http://www.cs.binghamton.edu/~reckert/460/texture.htm

- Persistence of Vision Ray Tracer (free):
  http://povray.org/

Ray Tracing

- What is seen by viewer depends on:
  - rays of light that arrive at his/her eye

- So to get “correct” results:
  - Follow all rays of light from all light sources
  - Each time one hits an object, compute the reflected color/intensity
  - Store results for those that go through projection plane pixels into observer’s eye
  - Paint each pixel in the resulting color
Forward Ray Tracing

- Infinite number of rays from each source
- At each intersection with an object
  - could have an infinite number of reflected rays
- Completely intractable
- Would take geological times to compute
Backward Ray Tracing

- Look **only** at rays observer sees
- Follow rays backwards from eye point through pixels on screen
  - “Eye” rays
- Check if they intersect objects
  - If so, can intersection point see a light source?
    - If so, compute intensity of reflected light
    - If not, point is in the shadow
  - If object has reflectivity/transparency
    - Follow reflected/transmission rays
    - Treat these rays as “eye” rays
    - So it's a recursive algorithm
Recursive Ray Tracing Algorithm

depth = 0
for each pixel (x,y)
    Calculate direction from eyepoint to pixel
    TraceRay (eyepoint, direction, depth, *color)
    FrameBuf [x,y] = color

Example Ray Intersection Calculation: An Eye Ray with a Sphere

TraceRay (start_pt, direction_vector, recur_depth, *color)
if (recur_depth > MAXDEPTH)   color = Background_color
else
    // Intersect ray with all objects
    // Find int. point that is closest to start_point
    // Hidden surface removal is built in
    if (no intersection)   color = Background_color
    else
        // Send out shadow rays toward light sources
        local_color = contribution of illumination model at int. pt.
        // Calculate direction of reflection ray
        TraceRay (int_pt, refl_dir., depth+1, *refl_color)
        // Calculate direction of transmitted ray
        TraceRay (int_pt, trans_dir., depth+1, *trans_color)
        color = Combine (local_color, refl_color, trans_color)
Combining Color from Reflection Ray

- Add attenuated reflected color intensity to local color intensity:
  \[ \text{color} = \text{local\_color} + k \times \text{refl\_color} \]
  - here refl\_color is \( I(r,g,b) \) - color returned by reflection ray
  - local\_color is \( I(r,g,b) \) - color computed by illumination model at intersection point
  - \( k \) is an attenuation factor (<1)

Combining Color from Transmission Ray

- Observer sees a mixture of light reflected off surface and light transmitted through surface
- So combine colors (interpolate)
  \[ I(r,g,b) = k' \times I_{\text{local}}(r,g,b) + (1 - k') \times I_{\text{transmitted}}(r,g,b) \]
  - \( k' \) is opacity factor coefficient
  - \( k' = 0 \) => perfectly transparent, \( k' = 1 \) => perfectly opaque
Ray Tracing Intersection Calculations

Example Ray Intersection Calculation: An Eye Ray with a Sphere

Parametric Equations for Eye Ray:

\[ x = x_0 + (x_1-x_0)t \]
\[ x = x_0 + \Delta x^*t \]
\[ y = y_0 + (y_1-y_0)t \]
\[ y = y_0 + \Delta y^*t \]
\[ z = z_0 + (z_1-z_0)t \]
\[ z = z_0 + \Delta z^*t \]
Equation of a sphere of radius $r$, centered at $(a,b,c)$

$$(x-a)^2 + (y-b)^2 + (z-c)^2 = r^2$$

Substitute ray parametric equations:

$$(x_0+\Delta x^*t-a)^2 + (y_0+\Delta y^*t-b)^2 + (z_0+\Delta z^*t-c)^2 = r^2$$

Rearrange terms:

$$((\Delta x^2+\Delta y^2+\Delta z^2)t^2 + 2[\Delta x(x_0-a)+\Delta y(y_0-b)+\Delta z(z_0-c)]t
+(x_0-a)^2 + (y_0-b)^2 + (z_0-c)^2 - r^2 = 0$$

This is a quadratic in parameter $t$

- **Solution(s):** value(s) of $t$ where ray intersects sphere
- **Three cases**
  - No real roots ==> no intersection point
  - 1 real root ==> ray grazes sphere
  - 2 real roots ==> ray passes thru sphere
    - Select smaller $t$ (closer to source)
Sphere Normal Computation

- To apply illumination model at intersection point P, need surface normal
- Can show: $N = \left( \frac{x-a}{r}, \frac{y-b}{r}, \frac{z-c}{r} \right)$

Intersections with other Objects

- Handled in similar fashion
- May be difficult to come up with equations for their surfaces
- Sometimes approximation methods must be used to compute intersections of rays with surfaces
Disadvantages of Ray Tracing

- Computationally intensive
  - But there are several acceleration techniques
- Bad for scenes with lots of diffuse reflection
  - But can be combined with other algorithms that handle diffuse reflection well
- Prone to aliasing
  - One sample per pixel
    - can give ugly artifacts
  - But there are anti-aliasing techniques
Persistence of Vision Ray Tracer

- POVRay free software
- Lots of capabilities
- Great for playing around with ray tracing
  - http://povray.org/

An Algorithm Animation of a Ray Tracer

Ray Tracing Algorithm Animator in VC++
(with David Goldman)
See:
http://www.cs.binghamton.edu/~reckert/3daape_paper.htm

Ray Tracing Algorithm Animation Java Applet and Paper (with Brian Maltzan)
See:
http://www.cs.binghamton.edu/~reckert/brian/index.html
Pattern/Texture Mapping

- Adding details or features to surfaces
  - (variations in color or texture)

General Texture Mapping

- Pattern Mapping Technique
  - Modulate surface color calculated by reflection model according to a pattern defined by a texture function
    - (“wrap” pattern around surface)
    - 2-D Texture function: \( T(u,v) \)
      - Define in a 2-D texture space \((u,v)\)
      - Could be a digitized image
      - Or a procedurally-defined pattern
Inverse Pixel Mapping (Screen Scanning)

For each pixel on screen \((xs, ys)\)
- Compute \(pt (x, y, z)\) on closest surface projecting to pixel (e.g., ray tracing)
- Determine color (e.g., apply illumination/reflection model)
- Compute \((u, v)\) corresponding to \((x, y, z)\) (inverse mapping)
- Modulate color of \((xs, ys)\) according to value of \(T(u, v)\) at \((u, v)\)

Inverse Mapping a Sphere
- Lines of longitude: constant \(u\), corresponds to \(\theta\)
- Lines of latitude: constant \(v\), corresponds to \(\phi\)

\[
x = R \sin(\phi) \cos(\theta)
\]
\[
y = R \sin(\phi) \sin(\theta)
\]
\[
z = R \cos(\phi)
\]

\[
\phi = \arccos(z/R) = \arccos(N_x, N_z)
\]
\[
\theta = \arccos(x/R \sin(\phi))
\]

\[
v = (p \cdot \phi)/\pi
\]
\[\phi = 0, \text{ North Pole, } v = 1\]
\[\phi = \pi, \text{ South Pole, } v = 0\]

\[
u = \theta/2\pi \text{ if } N_y > 0 \quad \theta > 0, \text{ if } N_x = 0\]
\[
u = 1 - \theta/2\pi \text{ if } N_y < 0 \quad \theta < 0, \text{ if } N_x = 0\]
Ex: Inverse Mapping a Polygon

- Choose axis S (unit vector) along a polygon edge
  - will align with u-axis in texture space
- Choose a polygon vertex Po(x₀,y₀,z₀)
  - will correspond to origin in texture space
- Choose a scaling factor k
  - k = max dimension of polygon
    - 0-k in object space → 0-1 in texture space
  - Want to map point P(x,y,z) on polygon to (u,v)

  ![Diagram of inverse mapping a polygon](image)

- Construct vector \( V = P - Po \)
- \( V \cdot S = k\cdot u \), projection of P onto S
- So \( u = \frac{V \cdot S}{k} \)
- Choose orthogonal axis T in polygon plane (T=NxS)
- \( v = \frac{V \cdot T}{k} \)

![Diagram of inverse mapping with equations](image)
There are lots of other Texture Mapping Techniques

See Section 10-17 of your text book

Radiosity Methods

- Alternative to ray tracing for handling global illumination
- Two kinds of illumination at each reflective surface
  - Local: from point sources
  - Global: light reflected from other surfaces in scene (multiple reflections)
- Ray tracing handles specularly reflected global illumination
  - But not diffusely reflected global illumination
Radiosity Approach

- Compute global illumination
- All light energy coming off a surface is the sum of:
  - Light emitted by the surface
  - Light from other surfaces reflected off the surface
  - Divide scene into patches that are perfect diffuse reflectors...
    - Reflected light is non-directional
  - and/or emitters

Definitions

- **Radiosity (B):**
  - Total light energy per unit area leaving a surface patch per unit time—sum of emitted and reflected energy (Brightness)

- **Emission (E):**
  - Energy per unit area emitted by the surface itself per unit time (Surfaces having nonzero E are light sources)
• **Reflectivity** (ρ):
  – Fraction of light reflected from a surface (a number between 0 and 1)

• **Form Factor** (Fij):
  – Fraction of light energy leaving patch i which arrives at patch j
    • Function only of geometry of environment

• **Conservation of energy for patch i:**
  – Total energy out = Energy emitted + Sum of energy from other patches reflected by patch i:

\[
B_i A_i = E_i A_i + \rho_i \sum B_j A_j F_{ji} \\
B_i = E_i + \rho_i \sum (B_j A_j / A_i) F_{ji}
\]
Principle of Reciprocity for Form Factors

- Reversing role of emitters and receivers:
  - Fraction of energy emitted by one and received by other would be same as fraction of energy going the other way
  - \( F_{ij} \cdot A_i = F_{ji} \cdot A_j \implies F_{ji} = \frac{A_i}{A_j} F_{ij} \)
  - So:
    \[
    B_i = E_i + \rho_i \cdot \sum B_j \cdot F_{ij}
    \]
    \[
    B_i - \rho_i \cdot \sum B_j \cdot F_{ij} = E_i
    \]
- Need to solve this system of equations for the radiosities \( B_i \)

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Radiosity -- Matrix Formulation and Solution

Assume \( N \) patches

\( F_{ii} = 0 \) -- Patch \( i \) receives no energy from itself

Rearranging and writing out the Radiosity equation:

\[
\begin{bmatrix}
1 & \rho_1 F_{12} & \rho_1 F_{13} & \cdots & \rho_1 F_{1N} \\
\rho_2 F_{21} & 1 & \rho_2 F_{23} & \cdots & \rho_2 F_{2N} \\
\vdots & \vdots & \ddots & \ddots & \vdots \\
\rho_N F_{N1} & \rho_N F_{N2} & \cdots & 1 \\
\end{bmatrix}
\begin{bmatrix}
B_1 \\
B_2 \\
\vdots \\
B_N \\
\end{bmatrix}
=
\begin{bmatrix}
E_1 \\
E_2 \\
\vdots \\
E_N \\
\end{bmatrix}
\]

This is the matrix equation: \( M \cdot B = E \)

The \( E_i \) and \( \rho_i \) are known, and the form factors \( F_{ij} \) can be calculated so that the matrix elements \( M_{ij} \) can be determined. Since the \( \rho_i \) and \( F_{ij} \) are all less than or equal to zero, matrix \( M \) is diagonally dominant, so the Gauss-Seidel iteration method is guaranteed to converge after a few iterations.
Gauss-Seidel Solution

\[ B_1 + M_{12}B_2 + \ldots + M_{1N}B_N = E_1 \]
\[ M_{21}B_1 + B_2 + \ldots + M_{2N}B_N = E_2 \]
\[ \vdots \]
\[ M_{N1}B_1 + M_{N2}B_2 + \ldots + B_N + M_{NN}B_N = E_N \]

Initial guess: \( B_i^{(0)} = E_i \)

Next iteration \( B_i^{(n+1)} = E_i - \left( M_{i1}B_1^{(n)} + \ldots + M_{iN}B_N^{(n)} + \ldots + M_{NN}B_N^{(n)} \right) \)

Continue iterating until all the difference between \( B_i^{(n+1)} \) and \( B_i^{(n)} \) is small enough for all patches.

Notice that for each patch \( i \) we are "gathering" radiosity from all the other patches.

Thus the scene is not finished until we have processed all patches—very time consuming.

Problem: getting form factors

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Computing Form Factors

Form Factor Determination

The form factor \( F_{ij} \) from patch \( i \) to patch \( j \) is obtained in principle by by integrating over both patches:

\[ F_{ij} = \frac{1}{\epsilon_{i,j} A_i A_j} \int_{\Delta A_i} \cos \phi_i \cos \phi_j \frac{\Delta A_j}{\pi r^2} \]

But this is very difficult.

\[ \Delta FF = \Sigma \left( \cos \phi_i \cos \phi_j \Delta A_j \right) / (\pi r^2) \], approximately
**Hemicube Approximation**

Calculate and store the delta form factors for each element of the hemicube.

\[ F_i = \sum_{j} \Delta F_{ij} \]

To calculate the form factor \( F_{ij} \), build a hemicube centered on patch \( i \) and sum the delta form factors for those elements of the hemicube to which patch \( j \) projects.

**Hemicube Pixel Computations**

\[ \Delta F = \cos \theta_i \cos \theta_p \Delta A / (\pi r^2) \]

a. (top) \( \Delta F = \Delta A / [\pi (x^2 + y^2 + 1)^2] \)

b. (sides) \( \Delta F = z \Delta A / [\pi (y^2 + z^2 + 1)^2] \)
Hemicube Form Factor Algorithm

Compute & store all hemicube delta Form Factors: \( \Delta FF[k] \)
Zero all the Form Factors: \( F_{ij} \)
For all patches \( i \)
  Place unit hemicube at center of patch \( i \)
  For each cell \( k \) on hemicube
    \( \text{dist}[k] = \infty \)
  For each patch \( j \) (\( j \neq i \))
    If line from origin through cell \( k \) intersects patch \( j \)
      compute distance \( d \) to intersection point
      if \( d < \text{dist}[k] \)
        \( \text{dist}[k] = d \)
      store \( j \) in item_buf \([k]\)
  For each cell \( k \) on hemicube
    \( j = \text{item}_\text{buf}[k] \)
  \( F_{ij} = F_{ij} + \Delta FF[k] \)

Video of Radiosity Form Factor Computation
Steps in Applying Radiosity Method

Summary of Steps:
Define a scene.
Divide scene into distinct patches.
Build a hemicube on each patch and calculate the delta form factors for cell on every hemicube.
Calculate a form factor for every pair of patches in the scene.
Calculate the red, green, and blue radiosities for each patch.
Map all radiosity values to a 0 - 255 color scale.
Apply Gouraud shading.

Three Simple Radiosity Images

After 1st Gauss-Seidel Iteration
No Gouraud Shading
Gouraud Shading
Radiosity Summary

- Good for scenes with lots of diffuse reflection
- Not good for scenes with lots of specular reflection
  - Complementary to Ray Tracing
  - But can be combined with Ray Tracing
- Very computationally intensive
  - Can take very long times for complex scenes
    - but once patch intensities are computed, scene “walkthroughs” are fast
  - Gauss-Seidel is very memory intensive
  - There are other approaches
    - Progressive Refinement